

# The Art of Bayesian Model Checking

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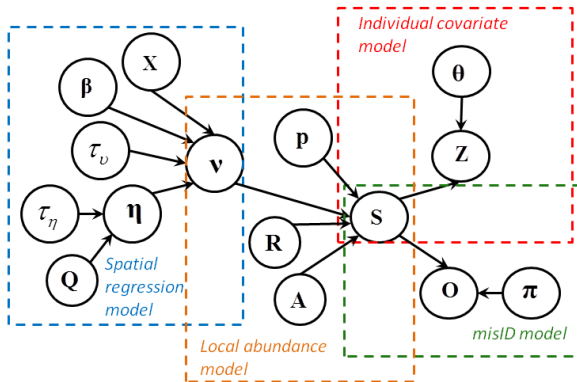
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# Outline

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- ▶ GOF for integrated population models (Besbeas and Morgan 2014)

## Background

- ▶ What this talk is *not*: introduction to Bayesian inference, model convergence diagnostics, model selection
- ▶ How do you go about assessing goodness-of-fit in a big hierarchical model?



## Code and dependencies

- ▶ Presentation and R Markdown code available at [www.github.com/pconn/BMC\\_CAPAM\\_talk](https://www.github.com/pconn/BMC_CAPAM_talk)
- ▶ Some functions from HierarchicalGOF R package, install available at [www.github.com/pconn/HierarchicalGOF](https://www.github.com/pconn/HierarchicalGOF)

NB: This package accompanied Conn et al. (2018); never intended for production level use!

- ▶ Some of these diagnostics are in the DHARMA R package (Hartig 2021)

# Notation

- ▶ Bold: vector or matrix
- ▶  $[\boldsymbol{\theta}]$  : Marginal distribution of  $\boldsymbol{\theta}$
- ▶  $[\mathbf{y}|\boldsymbol{\theta}]$ : Conditional distribution of  $\mathbf{y}$  given  $\boldsymbol{\theta}$
- ▶  $f(y_i|\boldsymbol{\theta})$ : Probability mass or density function evaluated at  $y_i$
- ▶  $F(y_i|\boldsymbol{\theta}) = \int_{-\infty}^{y_i} f(z|\boldsymbol{\theta})dz$ : Cumulative mass or density function evaluated at  $y_i$
- ▶  $[\mathbf{y}^{rep}|\mathbf{y}] = \int [\mathbf{y}^{rep}|\boldsymbol{\theta}][\boldsymbol{\theta}|\mathbf{y}]d\boldsymbol{\theta}$ : Posterior predictive distribution

## Example dataset

Simulated spatial count dataset (think CPUE index standardization with spatially autocorrelated random effects) with 200 randomly sampled locations.

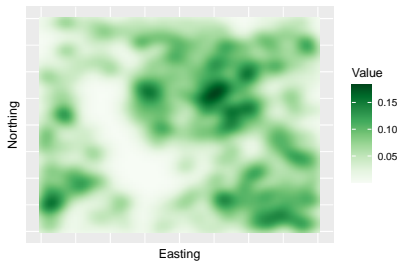
$$y_i \sim \text{Poisson}(\exp(\mathbf{x}'_i \boldsymbol{\beta} + \eta_i + \epsilon_i))$$

$$\boldsymbol{\eta} \sim \text{Predictive-process-exponential}(\theta, \tau_\eta)$$

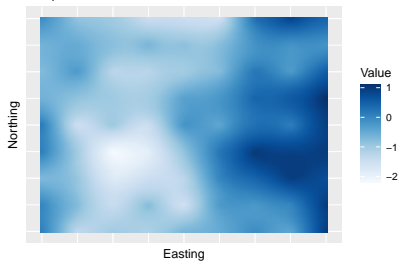
$$\epsilon_i \sim \text{Normal}(0, 1/\tau_\epsilon)$$

# Example dataset

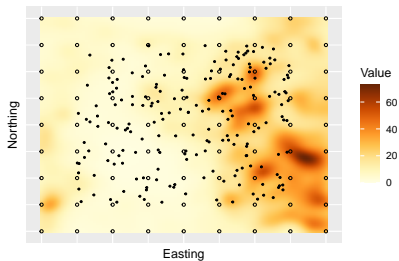
A. Covariate



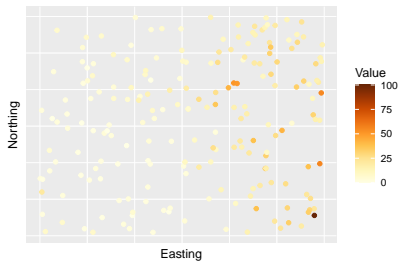
B. Spatial random effects



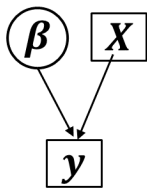
C. Expected abundance



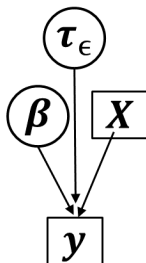
D. Simulated count



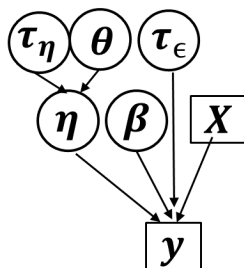
## Example estimation models



Simple Bayesian Poisson  
GLM (no random effects)



Bayesian Poisson GLMM  
w/ overdispersion only



Bayesian Poisson GLMM  
w/ overdispersion and  
spatially autocorrelated  
random effects

DAGs for count data



# Posterior predictive checks

Posterior predictive distribution:

$$[\mathbf{y}^{rep} | \mathbf{y}] = \int [\mathbf{y}^{rep} | \boldsymbol{\theta}] [\boldsymbol{\theta} | \mathbf{y}] d\boldsymbol{\theta}$$

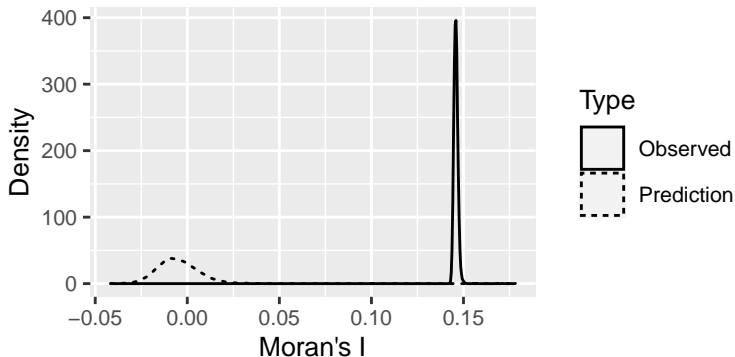
Practically:

1. Sample from the posterior  $\boldsymbol{\theta}^{rep} \sim [\boldsymbol{\theta} | \mathbf{y}]$
2. Generate replicated posterior predictive data  $\mathbf{y}^{rep} | \boldsymbol{\theta}^{rep}$ .
3. Compare real data to simulated data in some fashion. Do they look similar?

## Graphical checks

Many possible checks, perhaps used more informally since assessment of fit from graphs is somewhat subjective. See, e.g. `bayesplot` library for Stan users.

Example: Generate “null” distribution of Moran-I statistic values for posterior predictions and compare to those for observed data (shown: Bayesian GLM)



## Discrepancy functions - $T(\mathbf{y}, \theta)$

Are my data similar to those simulated from a model (i.e., posterior predictions)?

- Omnibus: e.g., Chi-square, Freeman-Tukey, Deviance, Likelihood ratio
- Targeted: Quantiles, Proportion of zeros, Moran's I of residuals
- Pivotal: Stay tuned!

## Bayesian p-values

Historically, this is the most frequently reported Bayesian model checking procedure.

$$P \leftarrow 0$$

**for**  $i \in 1 : m$  **do**

Draw  $\theta_i \sim [\theta | \mathbf{y}]$

Draw  $\mathbf{y}_i^{rep} \sim [\mathbf{y} | \theta_i]$

Calculate  $T_i^{rep} = T(\mathbf{y}_i^{rep}, \theta_i)$

Calculate  $T_i^{obs} = T(\mathbf{y}, \theta_i)$

**if**  $T_i^{obs} < T_i^{rep}$  **then**

$$P \leftarrow P + 1$$

**end if**

**end for**

$$P \leftarrow P/m$$

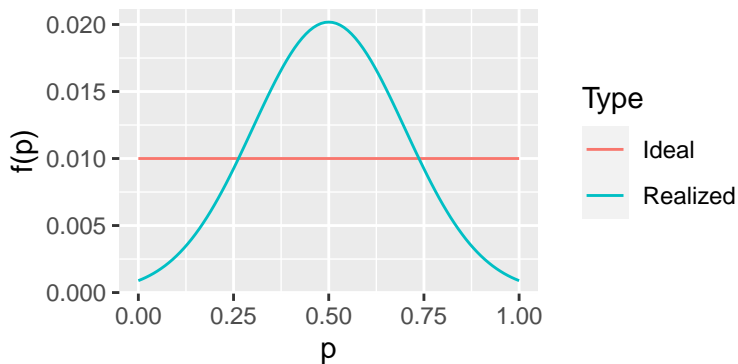
## Bayesian p-values for spatial regression example

	F-T	ChiSq	Moran	Zeroes	Tail
GLM	0.00	0.00	0.00	0.50	0.00
GLMM-Simple	0.55	0.55	0.00	0.20	0.90
GLMM-Spatial	0.39	0.42	0.79	0.29	0.61

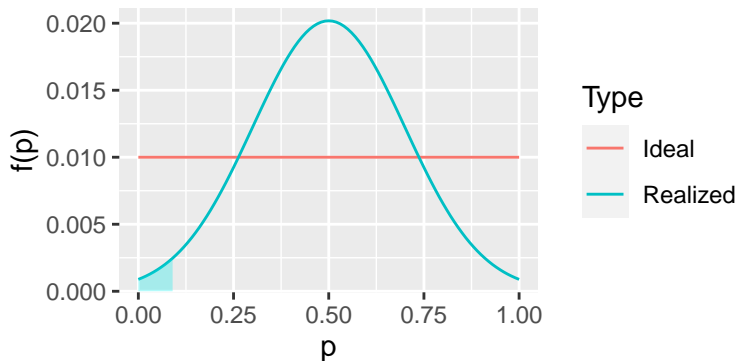
## Bayesian P-values: problems with interpretation

Question: If data were repeatedly simulated under the same model that is used for estimation, what distribution of p-values would we hope to get?

## Bayesian P-values: problems with interpretation



## Bayesian P-values: problems with interpretation



Bayesian p-values are known to be conservative!! An extreme value is indicative of lack-of-fit, but a smallish one (e.g. 0.1) may or may not be problematic (in this case a calibrated p-value is 0.02!!)



## Sampled posterior p-values

$P \leftarrow 0$

Draw  $\theta \sim [\theta|\mathbf{y}]$

for  $i \in 1 : m$  do

Draw  $\mathbf{y}_i^{rep} \sim [\mathbf{y}|\theta]$

Calculate  $T_i^{rep} = T(\mathbf{y}_i^{rep}, \theta)$

Calculate  $T_i^{obs} = T(\mathbf{y}, \theta)$

if  $T_i^{obs} < T_i^{rep}$  then

$P \leftarrow P + 1$

end if

end for

$P \leftarrow P/m$



-Advantage: P-value distribution guaranteed to be uniform

-Disadvantage: Answer depends on random number seed!

## Pivotal discrepancy measures (Yuan and Johnson 2012)

Can be used to test lack-of-fit at any stage of a hierarchical model.

Two strategies:

1) Parametric: Use known distributional properties, e.g.,

$$Y \sim \mathcal{N}(\mu, \sigma^2) \rightarrow Z = \frac{Y - \mu}{\sigma} \sim \mathcal{N}(0, 1)$$

Here,  $Z$  is a pivotal quantity in that it's reference distribution does not depend on  $\mu$  or  $\sigma$ . Simply keep track of  $Z$  and compare to  $\mathcal{N}(0, 1)$ .

## Pivotal discrepancy measures

2) Use a probability integral transform (PIT)

Continuous:

$$F(y_{ij}|\boldsymbol{\theta}) \sim U(0, 1)$$

Discrete:

$$w_{ij} \sim U(0, 1) \text{ where}$$

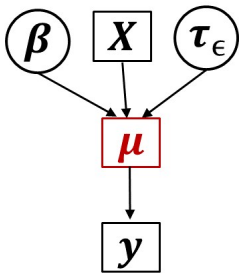
$$w_{ij} = F(y_{ij} - 1|\boldsymbol{\theta}) + u_{ij}f(y_{ij}|\boldsymbol{\theta}) \text{ and}$$

$$u_{ij} \sim U(0, 1)$$

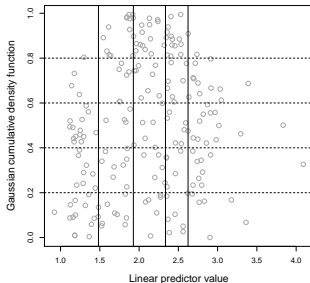
Here  $w_{ij}$  is called a “randomized quantile residual” (Dunn and Smyth 1996)

## Pivotal discrepancy measures

Application to spatial regression example. PIT test on simple GLMM using a  $\chi^2$  test for uniformity,



Bayesian Poisson GLMM  
w/ overdispersion only



A  $\chi^2$  discrepancy measure  
using PIT theory using a  
single sample of  $\theta$

The median  $\chi^2$  p-value computed in this way (taken across MCMC samples) was 0.37.

# Cross validation

Probably the gold standard!! But computationally intensive.

Spatial regression example: K-fold cross validation with 40 folds of 5 observations each - Simple GLMM model:

-Test for uniformity of empirical CDF:  $p = 0.13$

## Summary - Bayesian model checking

- Trade off between complexity and performance!
- Posterior predictive p-values, PIT tests are all fast and relatively easy to implement but are conservative. They can tell you when data fit a model terribly, but it is difficult to pinpoint small or moderate lack-of-fit
- Sampled posterior p-values have properly stated p-values but results can differ based on the posterior draw chosen
- Pivotal discrepancy measures allow you to examine fit at different levels of a hierarchical model
- Cross validation tests and calibrated p-values require considerably more investment (running Bayesian analyses iteratively)

## Bonus!! GOF for integrated population models

“Calibrated simulation” approach (Besbeas and Morgan 2014).  
Similar in spirit to Bayesian p-values.

1. Fit integrated population model; obtain MLEs,  $\hat{\theta}$  and associated variance-covariance matrix  $\hat{\Sigma}_{\theta}$
2. For  $k = 1, 2, \dots, n$ , simulate data  $\mathbf{y}_k \sim [\mathbf{y} | \tilde{\theta}_k]$  where  $\tilde{\theta}_k \sim \text{Multivariate-normal}(\hat{\theta}, \hat{\Sigma}_{\theta})$
3. Compare  $T(\mathbf{y}, \theta_k)$  with  $T(\mathbf{y}_k, \theta_k)$  in the same manner as in a Bayesian p-value for each dataset.
4. One can use a simulation study to look at what distribution of p-values one might expect under a “correct” model, and use these for calibration or to select a preferred discrepancy function.

## References

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- Conn, Paul B, Devin S Johnson, Perry J Williams, Sharon R Melin, and Mevin B Hooten. 2018. "A Guide to Bayesian Model Checking for Ecologists." *Ecological Monographs* 88 (4): 526–42.
- Dunn, Peter K, and Gordon K Smyth. 1996. "Randomized Quantile Residuals." *Journal of Computational and Graphical Statistics* 5 (3): 236–44.
- Hartig, Florian. 2021. *DHARMA: Residual Diagnostics for Hierarchical (Multi-Level / Mixed) Regression Models*. <http://florianhartig.github.io/DHARMA/>.
- Yuan, Y., and V. E. Johnson. 2012. "Goodness-of-Fit Diagnostics for Bayesian Hierarchical Models." *Biometrics* 68: 156–64.